

# MEXANIZMLAR TURLARI, ULARNING TUZILISHI VA QO'LLANILISHI

Reja:

- Fazoviy va tekis mexanizmlarning erkinlik darajalari
- Mashinalar turlari
- Mexanizmlar turlari va ularni qo'llanilishi.

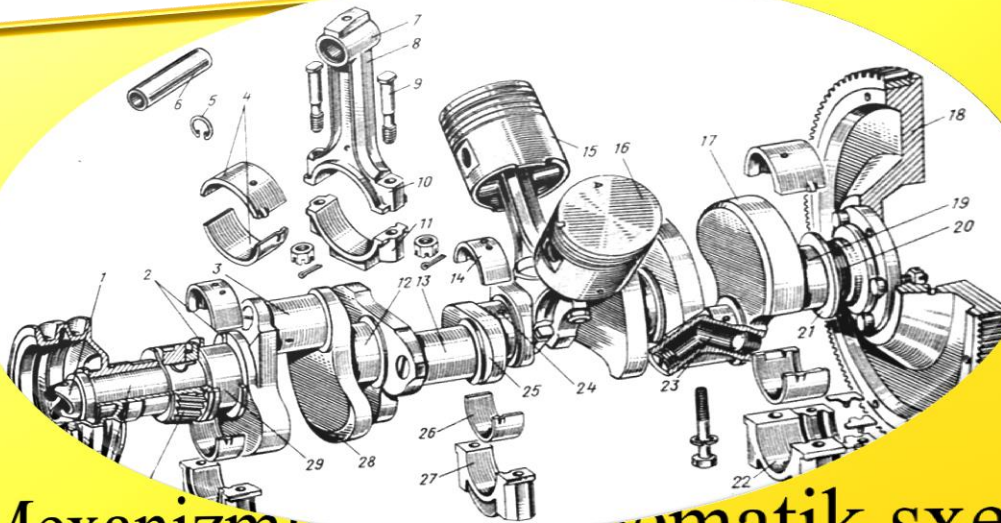
Bo'g'inlar qanday shaklga ega bo'lishidan qat'iy nazar ma'lum bir sxematik shaklga keltiriladi.



Bu sxematik shakl shartli belgi deb ataladi.



Bu shartli belgilar asosida mexanizmning kinematik sxemalari chiziladi.



Mexanizmlarning kinematik sxemasini chizish uchun uzunlik masshtabi tanlab olinadi va u asosida chiziladi. Har qanday mexanizm ma'lum bir erkinlik darajasiga ega.

$\mu_e$



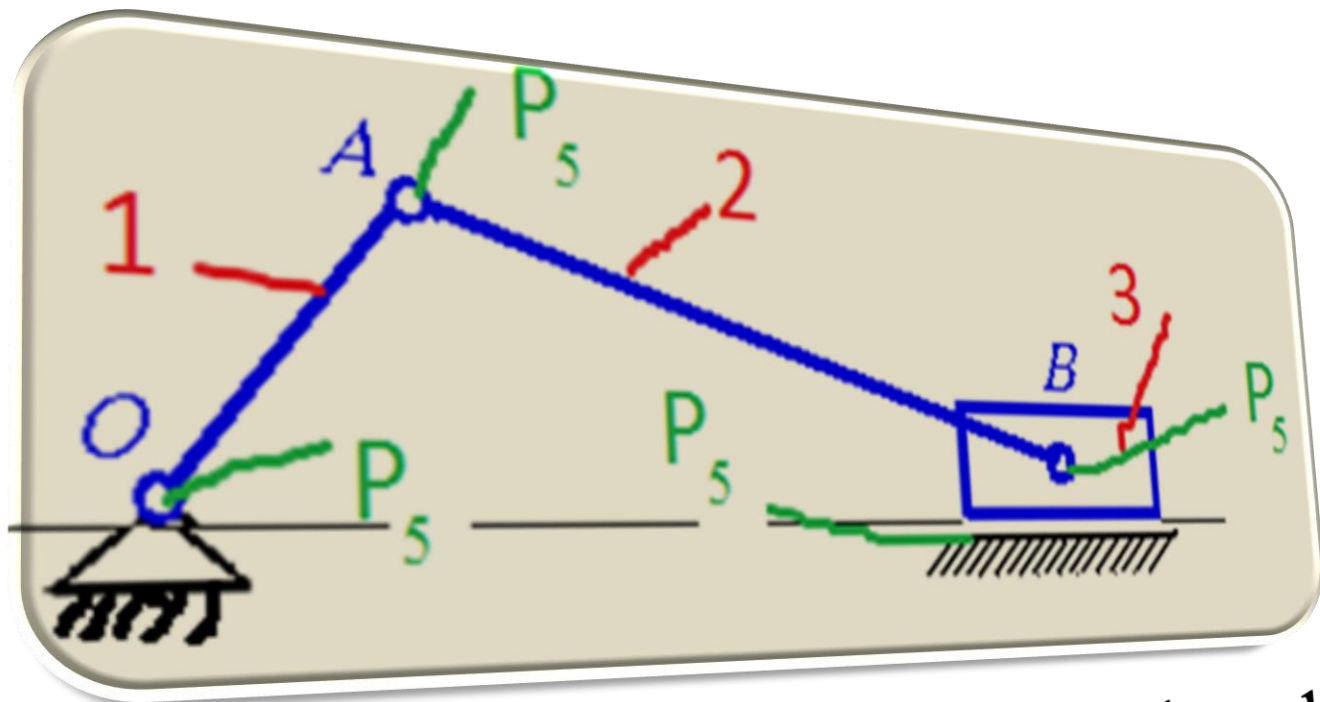
Tekis mexanizmlarning erkinlik darajasi  
“Chebishev” formulasi yordamida  
aniqlanadi.

$$W = 3n - 2P_5 - P_4$$

$n$  - qo'zg'aluvchan bo'g'inlar soni.

$P_5$  - beshinchi sinf kinematik jutlar soni

$P_4$  - to'rtinchi sinf kinematik juftlar soni



Yuqorida kirivoship polzunli mexanizimning kinematik sxemasi tasvirlangan



Fazoviy  
mexanizmning  
bo'g'in va kinematik  
nuqtalarini kinematik  
taxlil qilish bir necha  
usullarda bajariladi.

Ularning erkinlik darajasi  
Somov Malishev formulasi  
yo'rdamida aniqlanadi

$$W = 6n - 5 P_5 - 4 P_4 - 3P_3 - 2P_2 - P_1$$

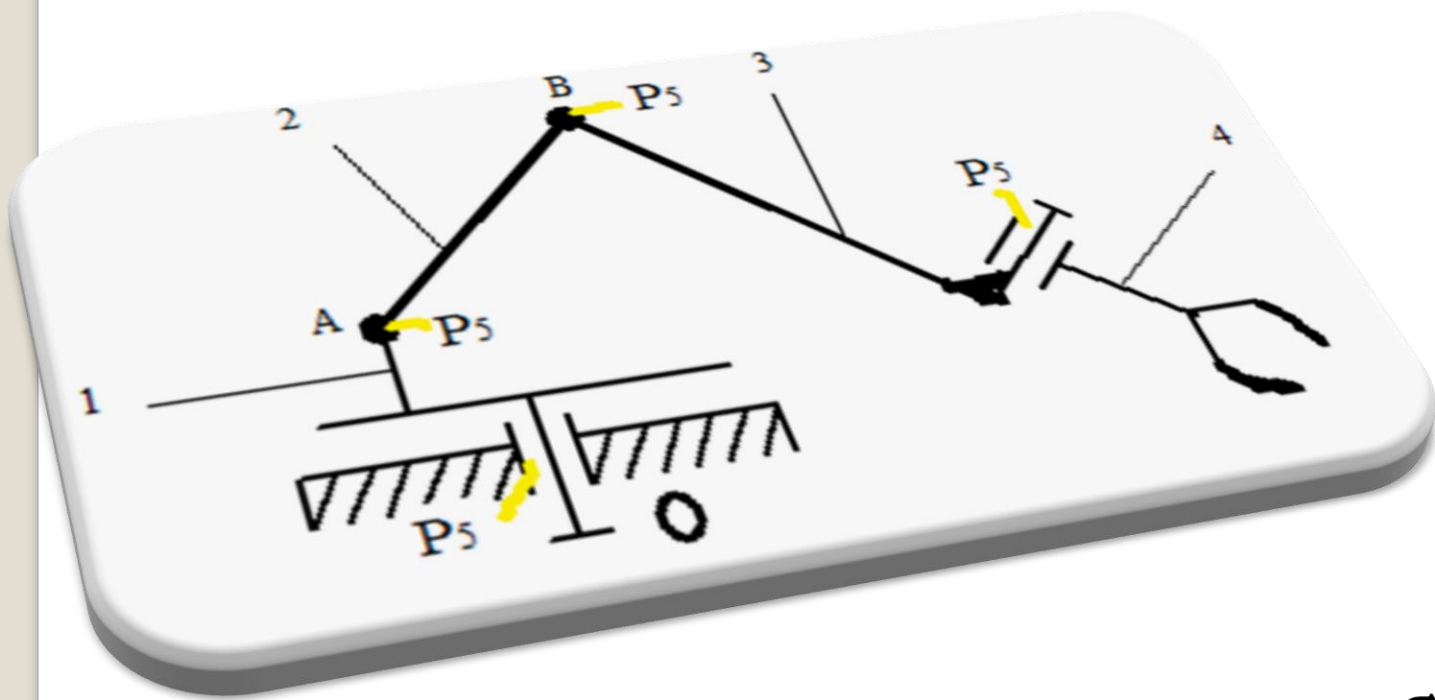
Bu yerda:

$n$  – qo'zg'aluvchan bo'g'inlar soni

$P_1$  – I sinf kinematik juftlar soni,  $P_2$  – II sinf kinematik juftlar soni,  $P_3$  – III sinf kinematik juftlar soni,  $P_4$  – IV sinf kinematik juftlar soni,  $P_5$  – V sinf kinematik juftlar soni



**Quyidagi maketda fazoviy  
mexanizm qo'llanilgan.**



Uning strukturaviy sxemasi  
quyidagicha chizilgan.

**Mashina deb – inson tomonidan yaratilgan, energiyani bir turdan boshqa turga o'zgartiruvchi yoki foydali ish bajarish maqsadida insonni aqliy yoki jismoniy mexnatini yengil-lashtiruvchi qurilmaga aytiladi.**

**Mexanizm deb – bir bo'g'inning harakatini boshqa bir bo'g'ning kerakli harakatiga aylantirib beruvchi bo'g'inlar sistemasiga aytiladi**

**Bo'g'in deb – mexanizm tarkibiga kiruvchi qattiq jismga aytiladi.**

**Sintez deb – berilgan parametrlar bo'yicha mexanizmni loyihalasga aytiladi.**

# Mashinalar turlari

- Texnologik mashinalar
- Transport mashinalari
- Energetik mashinalar
- Informatsion mashinalar
- Hisoblash mashinalari
- O'lchov mashinalari
- Kibernetik mashinalar

# MEXANIZMLARNING ASOSIY TURLARI

Richagli  
mexani-  
zmlar

Mush-  
takli  
mexani-  
zmlar

Tishli  
gildirakli  
mexani-  
zmlar

Vintli va  
pog'ona-  
li  
mexani-  
zmlar

Friksion  
mexani-  
zmlar

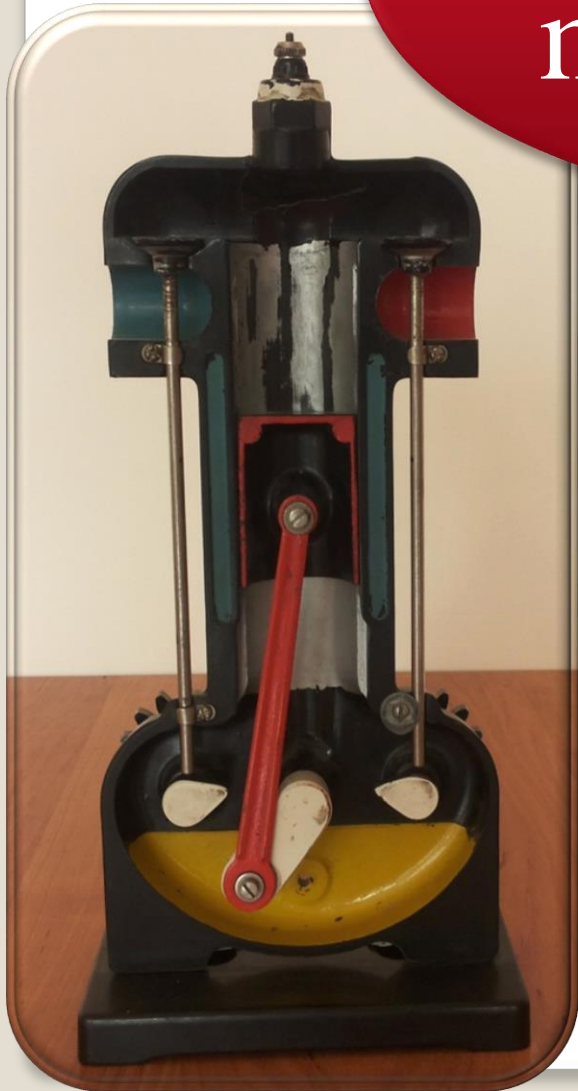
Egiluv-  
chan  
bo'g'inli  
mexani-  
zmlar

Elektro  
mexani-  
zmlar

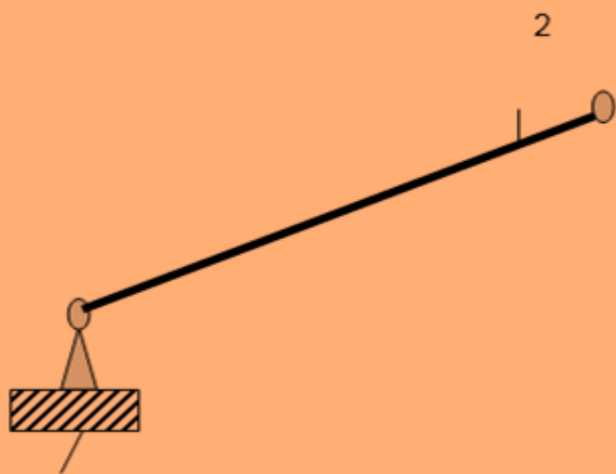
# **RICHAGLI MEXANIZMLAR TURLARI**

- **Oddiy mexanizmlar**
- **Murakkab mexanizmlar**

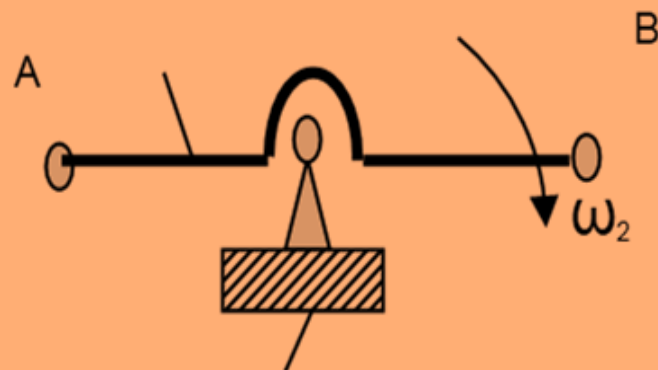
# Richagli mexanizmlar



# Oddiy mexanizmlar

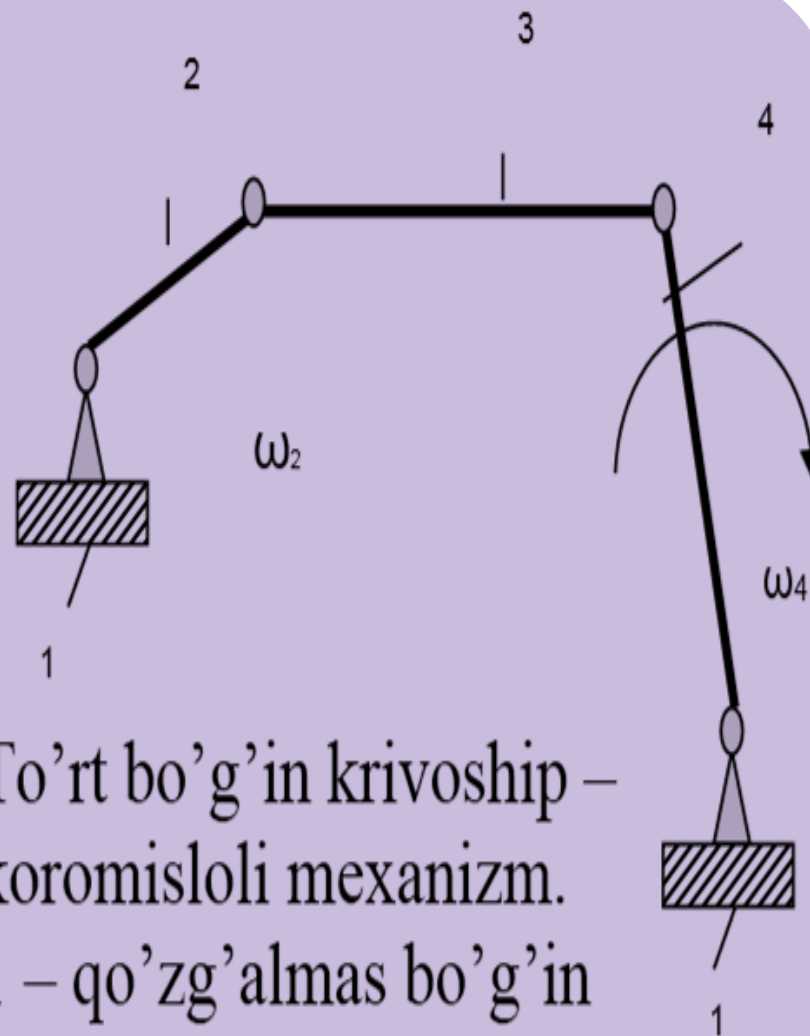


Ikki <sup>1</sup>bo'g'inli mexanizm  
1 – qo'zg'almas bo'g'in  
2 – qo'zg'aluvchan  
bo'g'in



Ikki yelkadan iborat ikki  
bo'g'inli mexanizm.  
1 – qo'zg'almas bo'g'in  
2 – qo'zg'aluvchan  
bo'g'in

# Murakkab mexanizm



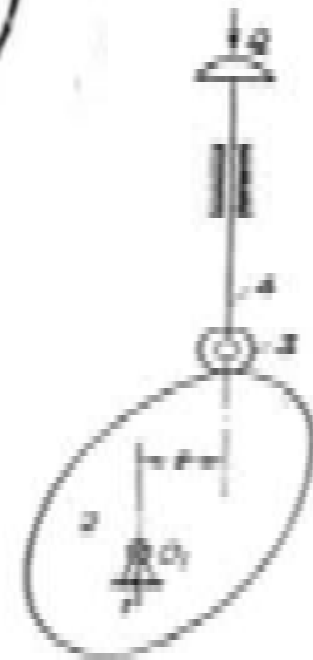
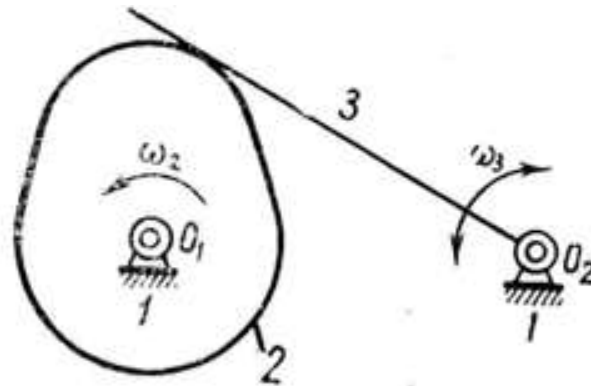
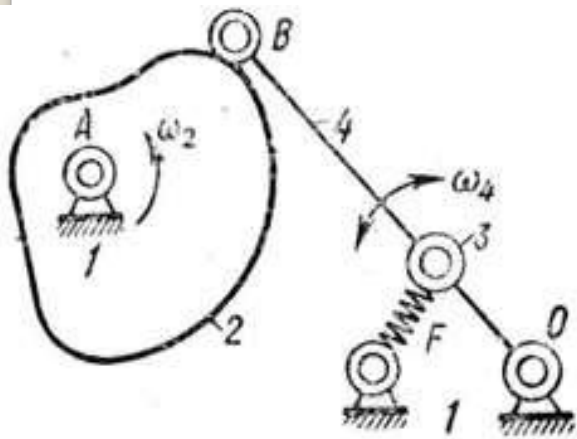
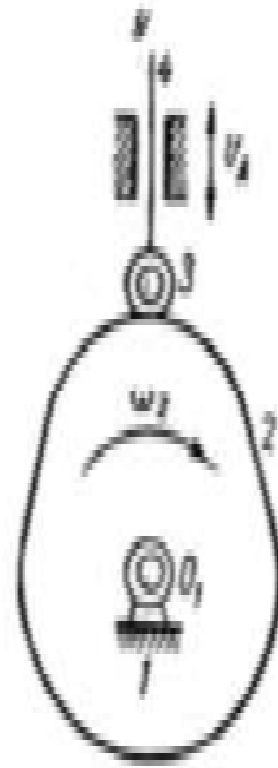
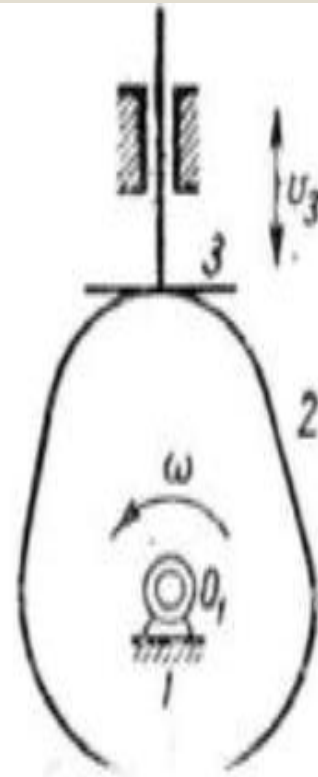
To'rt bo'g'in krivoship – koromisloli mexanizm.

1 – qo'zg'almas bo'g'in

2 – tirsakli val (krivoship)

3 – shatun, 4 - koromislo

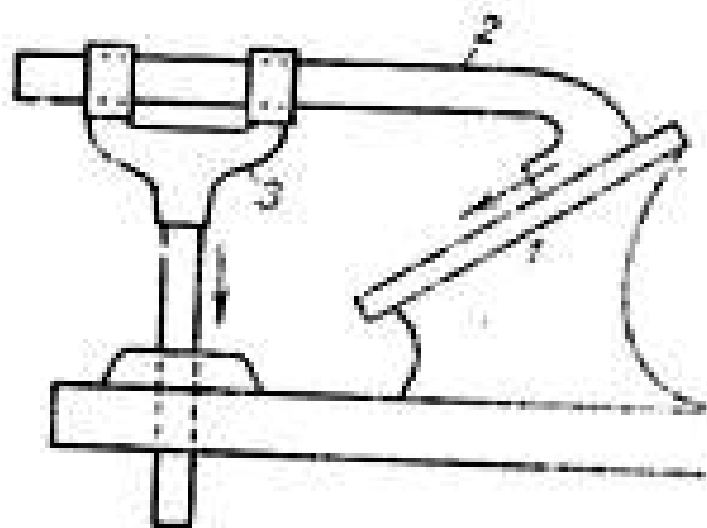
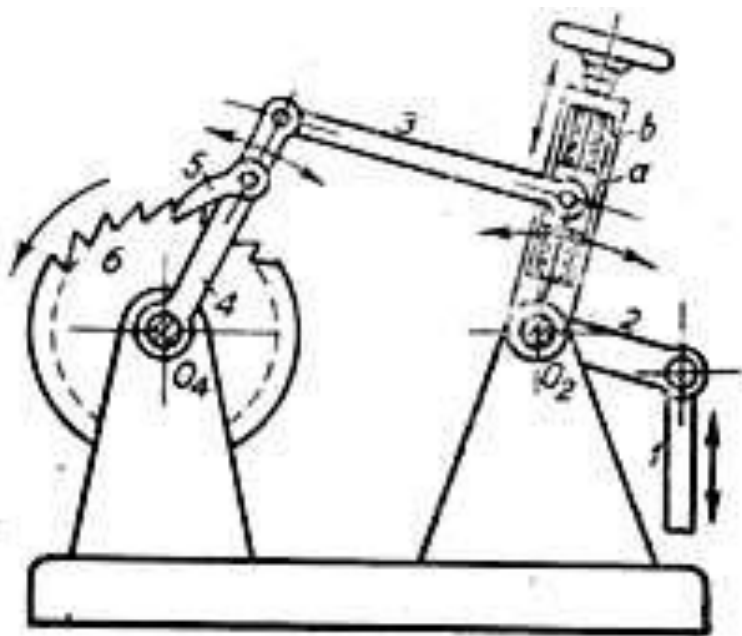
# Mushtakli mexanizmlar



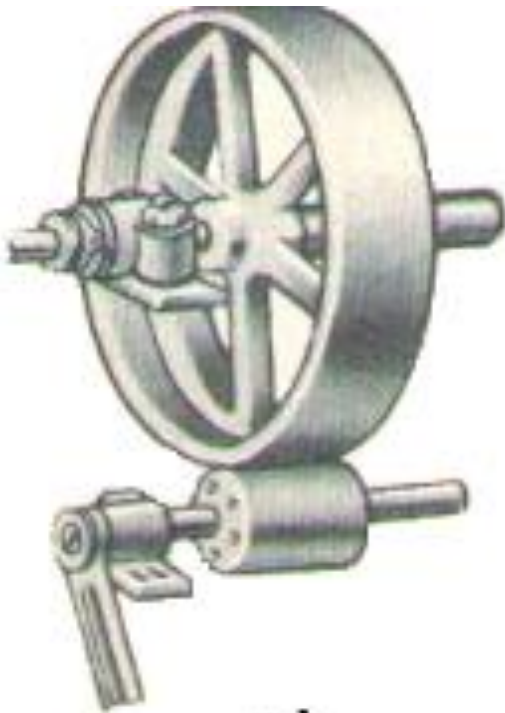
# Tishli g'ildirakli mexanizmlar



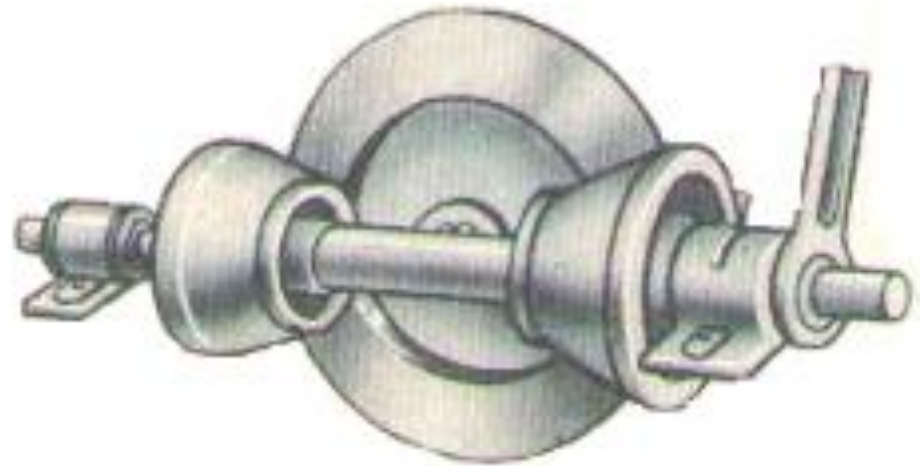
# Vintli va ponali mexanizmlar



# Friksion mexanizmlar

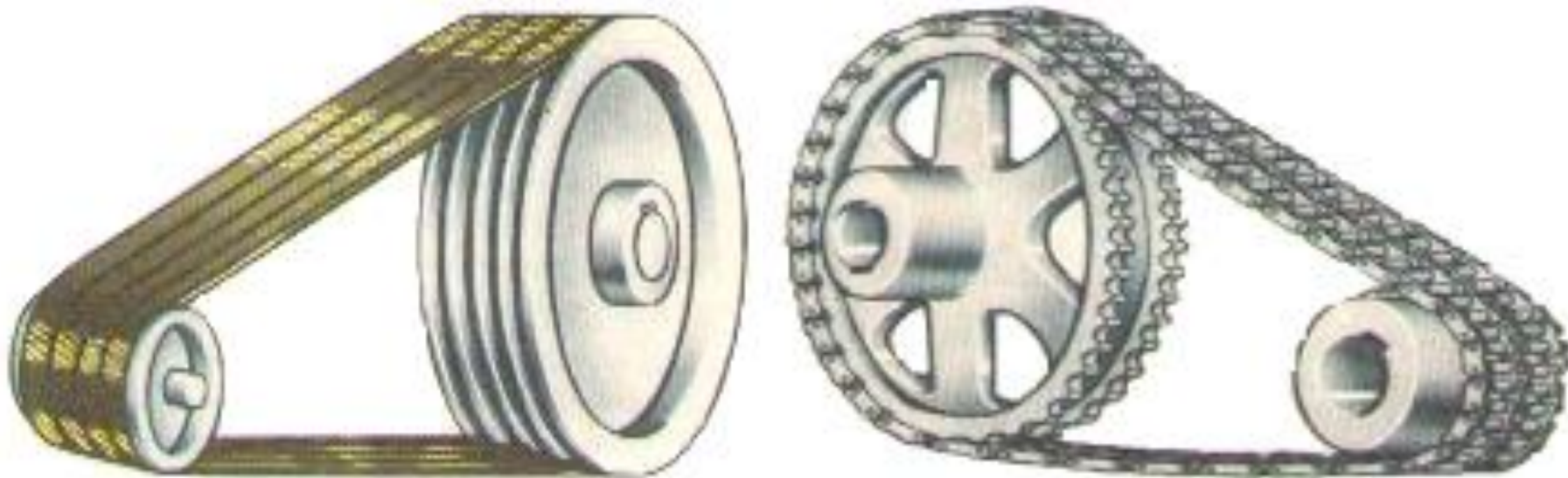


a)



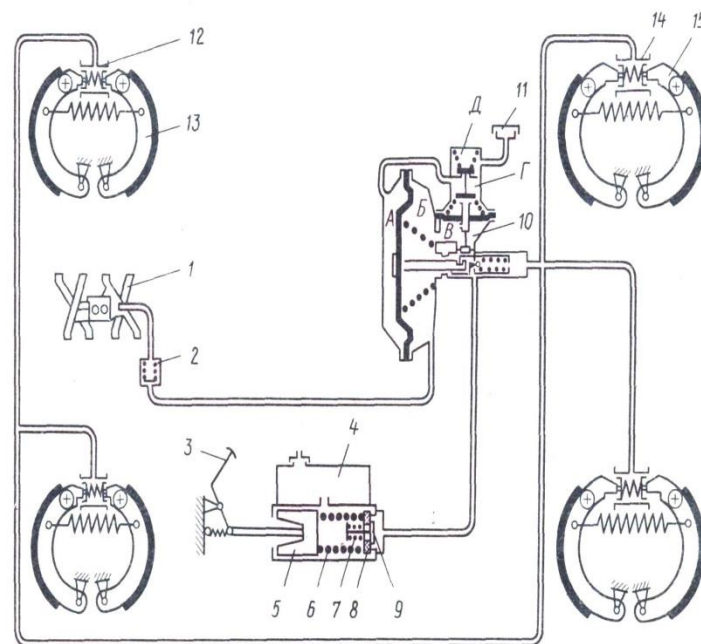
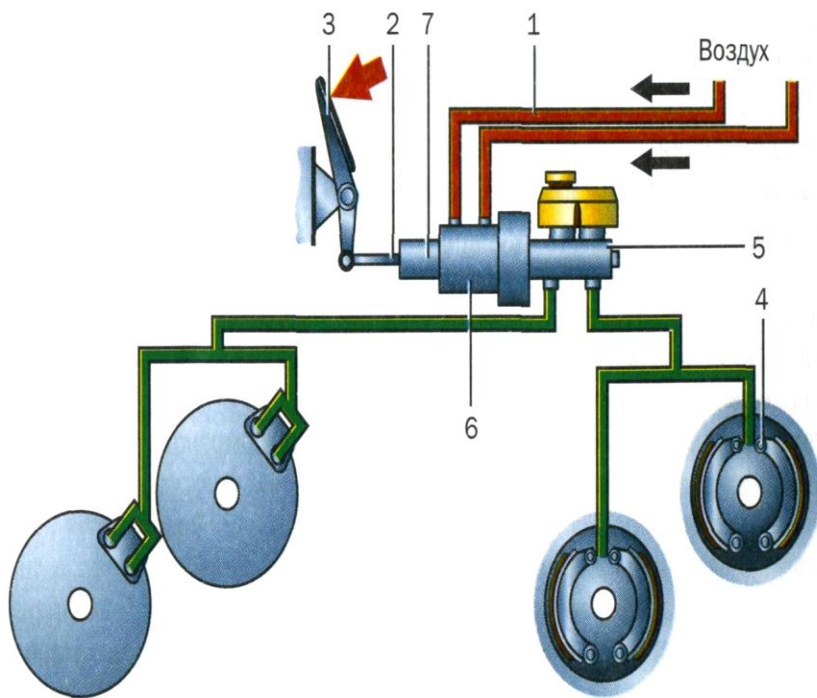
b)

# Egiluvchan bo'g'inli mexanizmlar

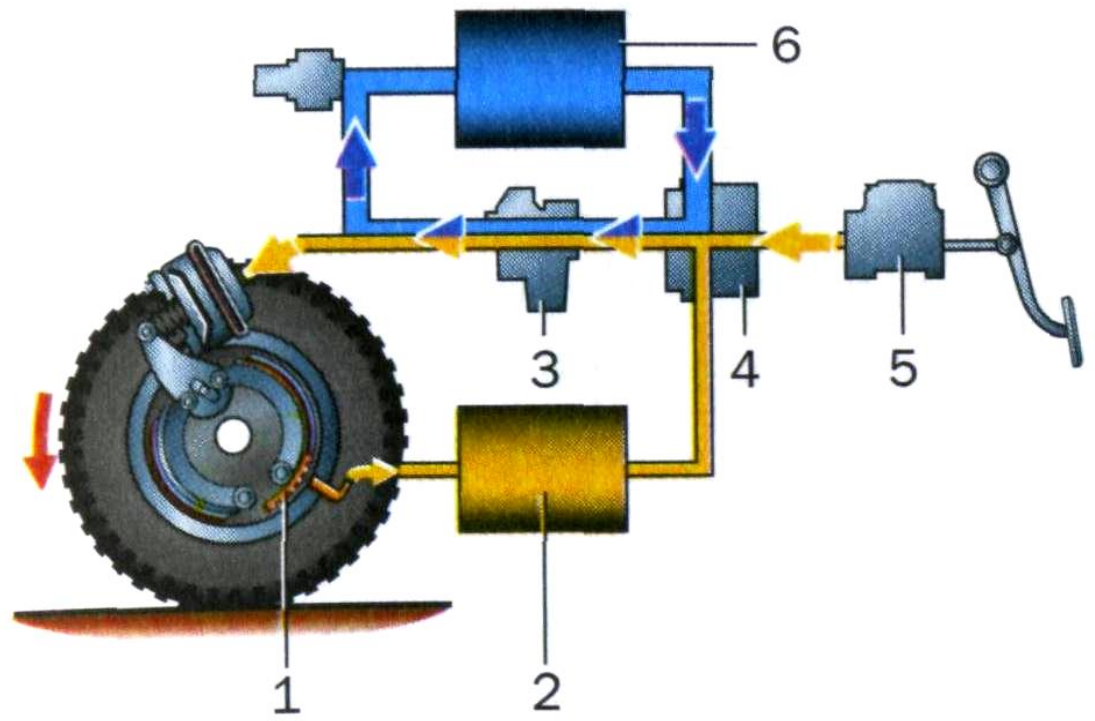
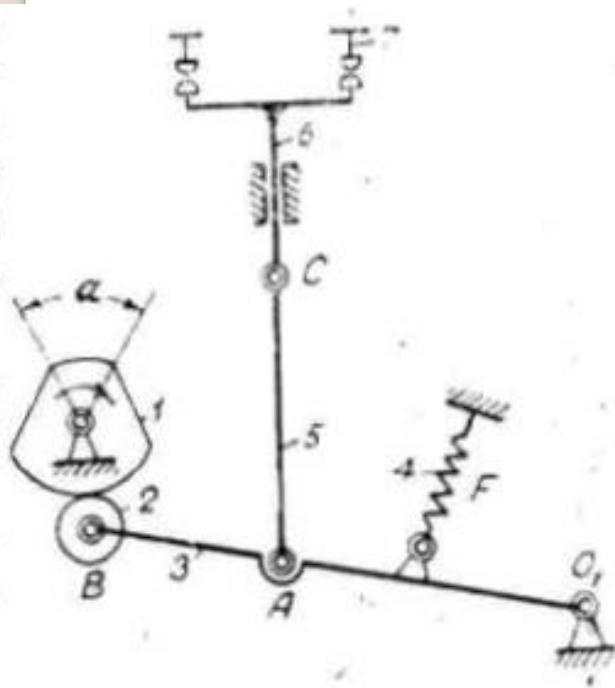


# Gidravlik va pnevmatik mexanizmlar

6



# Elektrik mexanizmlar



*E'tiboringiz  
uchun raxmat*