

# **Microprocessor Programming**

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# Microprocessor Programming

## Lecture 9 Procedures

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# Introduction

- A procedure is an important part of any computer system's architecture.
- It is a **group of instructions** that usually performs one task.
- Procedures allow programmers to **save time** by not having to rekey the same code over and over again.
- This **saves memory space** and makes it **easier to develop** software.

# Introduction (Cont.)

- Procedures are designed to return anywhere from zero to many values.
- Although there are ways to make it possible to utilize parameters, the simplest way to communicate between a program and a procedure is to use either **global variables or registers**.

# Procedures

- In assembly language, subprograms are called procedures.
- The actual procedure can be placed in a number of locations in the program.
- The most convenient place is **after the ENDP** statement in the main program and **prior to the END** statement.

# Layout of Procedures

- With the assembler, there are specific rules for storing procedures.
- A procedure begins with the **PROC directive** and ends with the **ENDP directive**.
- Each directive appears with the **name** of the procedure (e.g., pname).

```
pname proc  
.  
.  
pname endp
```

## Layout of Procedures (Cont.)

- Next comes the body of the procedure.
- Then, it is followed by the return instruction (**RET**) as shown below.
- The procedure uses a RET (return from procedure) instruction to bring the processor back to the point in the program where the procedure was called.

```
pname  proc  
        ; body of the procedure  
        ret  
pname  endp
```

## Layout of Procedures (Cont.)

- The PROC and ENDP directives indicate to the assembler the beginning and the end of the procedure respectively.
- During the execution of the procedure, the RET instruction forces the CPU to return to the location from where the procedure was called.

## Layout of Procedures (Cont.)

- In a procedure, it is better to include only one return statement to keep the program structured with only one entry point and one exit point.
- Also, it is usually best to be sure that the RET instruction is the last statement in a procedure prior to the ENDP directive.

# Layout of Procedures (Cont.)

- Here is an example procedure using only one RET instruction.

```
pro1    proc
        .if eax == 0
        mov edx,1
        .else
        mov edx, 0
        .endif
        ret
pro1    endp
```

# Call Instruction

- The instruction used to **invoke a procedure** is the CALL instruction.
- The CALL instruction has **one operand** that specifies the name of the procedure to be invoked.
- The CALL instruction calls a procedure by directing the processor to begin execution at a new memory location.
- Upon return from the procedure, execution will continue with the instruction after the CALL instruction.

`call      pname`

## Call Instruction (Cont.)

- If we want to implement one algorithm in two different locations of the same program, it would be much easier to call the procedure from two different locations in the main program as follow.

```
main    proc
        .
        call mult
        .
        .
        call mult
        .
        ret
main    endp
```

# Call Instruction (Cont.)

- Then, after the main program, the code for the algorithm (e.g., mult) could be written as a procedure.

```
mult    proc
        mov eax,0        ; initialize eax to 0
        .if x != 0
        mov ecx,1        ; initialize i to 1
        .while ecx<=y
        add eax,x        ; add x to eax
        inc ecx          ; increment i by 1
        .endw
        .endif
        ret
mult    endp
```

# Saving and Restoring Registers

- Not only in the main program but also in the procedures, registers are often needed to be saved and restored to backup their original contents.
- The following multiplication procedure includes saving and restoring the ecx register using PUSH and POP instructions.

```
mult    proc
        push ecx          ; save ecx
        mov eax,0         ; initialize eax to 0
        .if x != 0
        mov ecx,1         ; initialize i to 1
        .while ecx<=y
        add eax,x         ; add x to eax
        inc ecx           ; increment i by 1
        .endw
        .endif
        pop ecx           ; restore ecx
        ret
mult    endp
```

## **Saving and Restoring Registers (Cont.)**

- Although it is possible to save and restore all the registers whether they were altered or not, it does not help other programmers understand what is happening in the procedure.
- By saving and restoring only the registers that are altered, it helps others understand which registers are being altered and also helps make the code more self-documenting.
- However, there could be a chance for a logic error if the POP instructions were accidentally written in the wrong order.

## Saving and Restoring Registers (Cont.)

- Luckily, there is a way to save the four general purpose registers (eax, ebx, ecx, and edx) along with the esi, edi, ebp, and esp registers **with only one instruction**.
- The solution is to use **PUSHAD and POPAD instructions**.
- If a number of **32-bit registers** are modified in a procedure, use **PUSHAD at the beginning** of the procedure and **POPAD at the end** to save and restore the registers.

# Saving and Restoring Registers (Cont.)

## PUSHAD and POPAD Instructions

- The **PUSHAD** instruction pushes the contents of all of the **32-bit** general-purpose registers on the stack in the following order: `eax`, `ecx`, `edx`, `ebx`, `esp` (value before executing `PUSHAD`), `ebp`, `esi`, and `edi`.
- The **POPAD** instruction pops the same registers off the stack in reverse order.

# Saving and Restoring Registers (Cont.)

## Example

- Consider a procedure that outputs blank lines a variable number of times.
- In the following code, each of the four general purpose registers are **saved and restored individually**.

```
blankln  proc
          push eax
          push ebx
          push ecx
          push edx
          .repeat
          INVOKE printf, ADDR blankfmt
          dec ebx
          .until ebx<=0
          pop  edx
          pop  ecx
          pop  ebx
          pop  eax
          ret
blankln  endp
```

# Saving and Restoring Registers (Cont.)

## Example

- In the code below, the four general purpose registers are saved all at once using the **PUSHAD** and **POPAD** instructions.

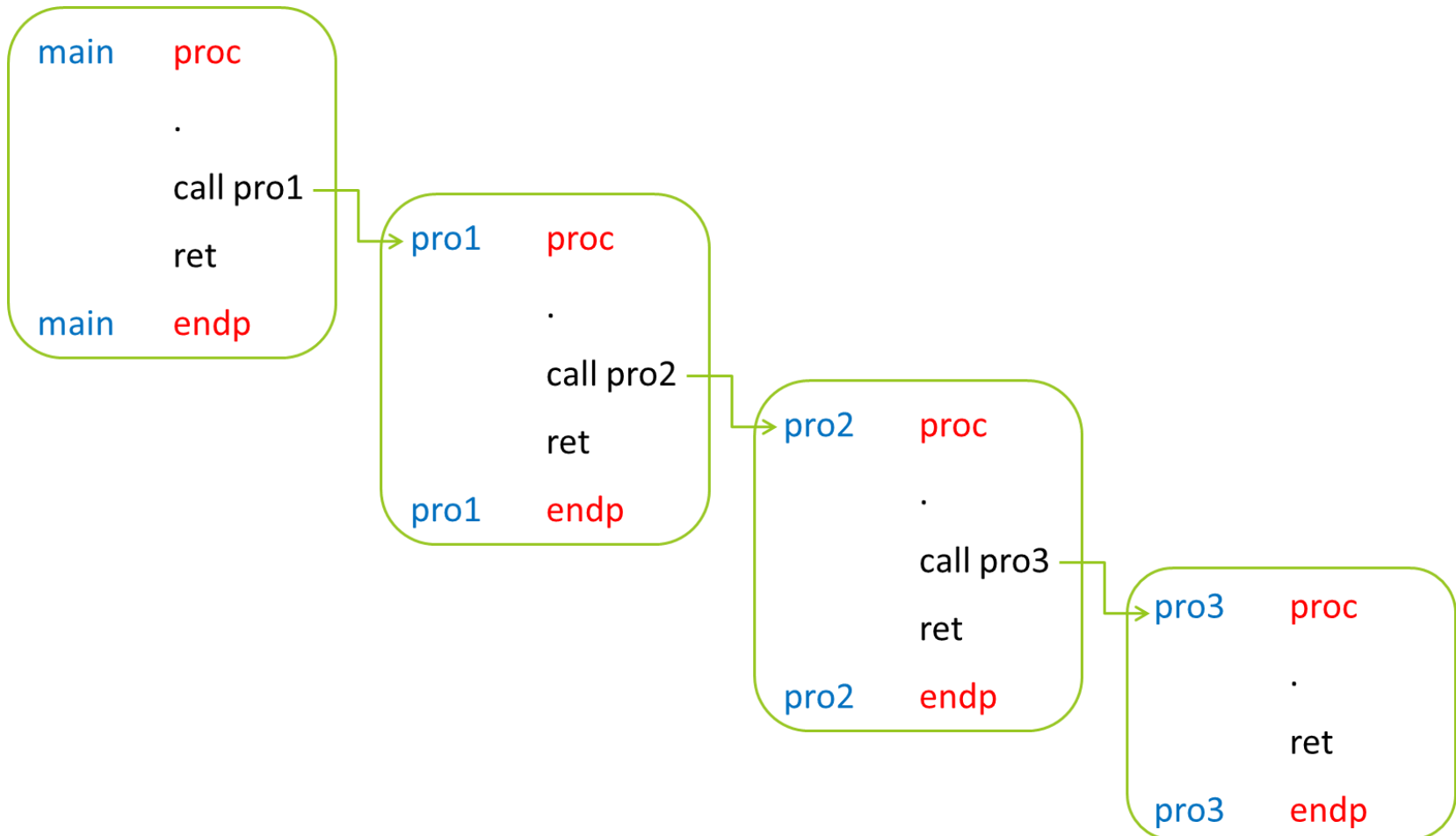
```
blankIn proc
    pushad
    .repeat
    INVOKE printf, ADDR blankfmt
    dec ebx
    .until ebx<=0
    popad
    ret
blankIn endp
```

# Nested Procedure Calls

- A nested procedure call occurs when a called procedure calls another procedure before the first procedure returns.
- For clearly understanding, we will consider a MASM code segments using nested procedure calls.
- Suppose that main program calls a procedure named pro1.
- While pro1 is executing, it calls the pro2 procedure.
- While pro2 is executing, it calls the pro3 procedure.

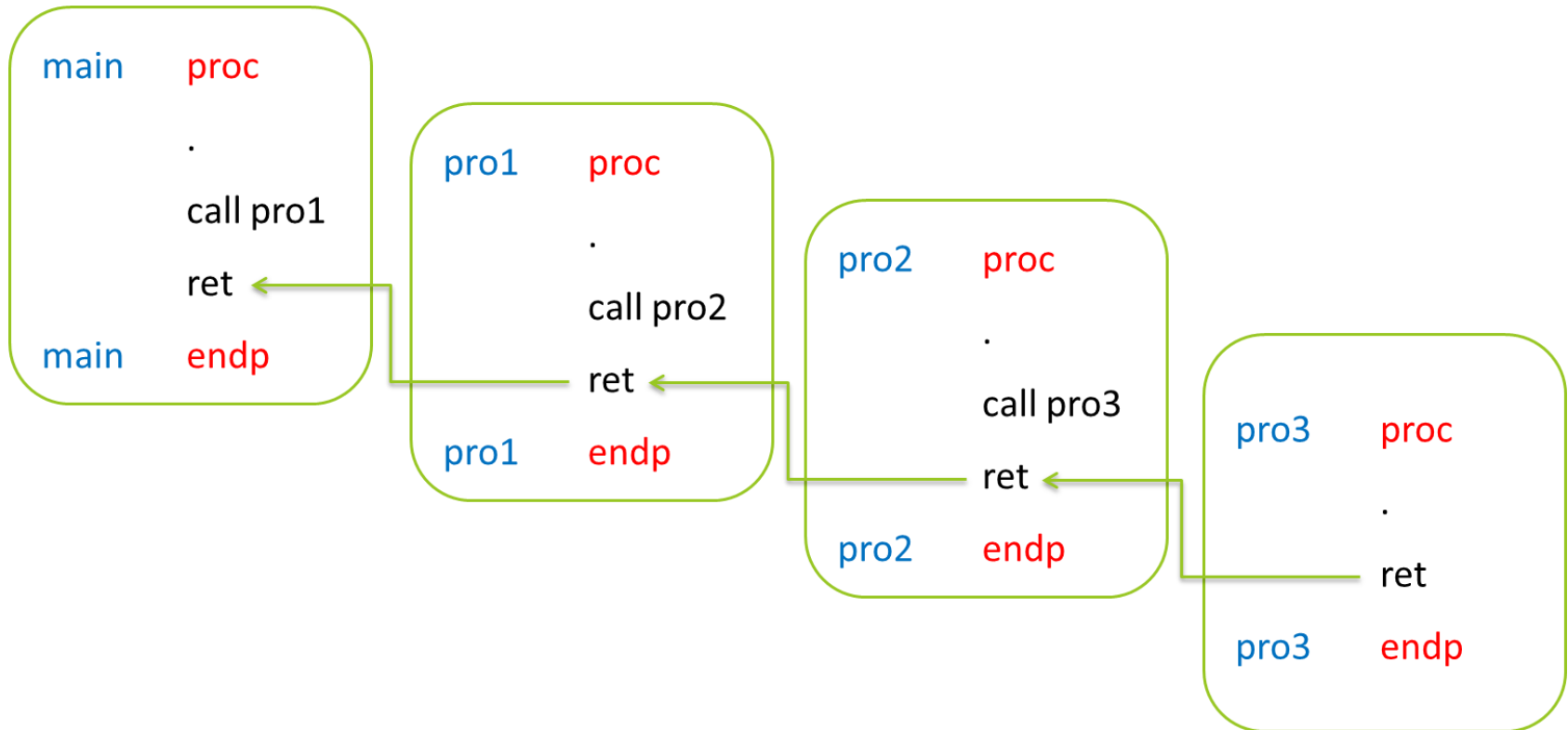
# Nested Procedure Calls (Cont.)

- The invoking process is shown in figure.



# Nested Procedure Calls (Cont.)

- The returning process is shown in figure.



## Nested Procedure Calls (Cont.)

- When the RET instruction at the end of pro3 executes, this causes execution to resume at the instruction following the call pro3 instruction.
- When the RET instruction at the end of pro2 executes, execution resumes at the instruction following the call pro2 instruction.
- Finally, when pro1 returns, execution resumes in main.

# Complete Program: Implementing the Power Function in a Procedure

- Consider the implementation of the power function ( $x^n$ ) in a procedure instead of having the code to calculate  $x^n$  in the main program.
- An iterative definition of the power function is as follows:

$x^n$  = If  $x < 0$  or  $n < 0$ , then negative message  
Else if  $x = 0$  and  $n = 0$ , then undefined message  
Else if  $n = 0$ , then 1  
Otherwise  $1 * x * x * \dots * x$  (n times)

# Complete Program: Implementing the Power Function in a Procedure

- For the sake of simplicity both here in the C program and more importantly in the subsequent assembly language program, power is implemented as a procedure (void function) and x, n, and ans are implemented as global variables.
- In addition to outputting a message in the case of an error, the procedure also returns a -1 in the variable ans.
- The procedure can then be invoked more than one time from the main program without having to duplicate the code each time.

# Complete Program: Implementing the Power Function in a Procedure

- The following is the implementation of the power function in a procedure in C code.

```
#include <stdio.h>
int x,n,ans;
int main() {
    void power();
    printf("%s", "Enter x: ");
    scanf("%d",&x);
    printf("%s", "Enter n: ");
    scanf("%d",&n);
    power();
    printf("\n%s%d\n\n", "The answer is: ",ans);
    return 0;
}

void power() {
    int i;
    ans=-1;
    if(x<0 || n<0)
        printf("\n%s\n", "Error: Negative x and/or y");
    else
        if(x==0 && n==0)
            printf("\n%s\n", "Error: Undefined answer");
        else {
            i=1;
            ans=1;
            while(i<=n) {
                ans=ans*x;
                i++;
            }
        }
}
```

# Complete Program: Implementing the Power Function in a Procedure

- The following is the implementation of the power function in a procedure in MASM code.

```
.listall
.386
.model flat,c
.stack 100h
scanf    PROTO arg2:Ptr Byte, inputlist:VARARG
printf   PROTO arg1:Ptr Byte, printlist:VARARG
.data
in1fmt   byte "%d",0
msg1fmt  byte "%s",0
msg3fmt  byte "%s%d",0Ah,0Ah,0
errfmt   byte "%s",0Ah,0
errmsg1  byte 0Ah,"Error: Negative x and/or y",0
errmsg2  byte 0Ah,"Error: Undefined answer",0
msg1     byte "Enter x: ",0
msg2     byte "Enter n: ",0
msg3     byte 0Ah,"The answer is: ",0
x        sdword ?
n        sdword ?
ans      sdword ?
.code
main     proc
    INVOKE printf, ADDR msg1fmt, ADDR msg1
    INVOKE scanf, ADDR in1fmt, ADDR x
    INVOKE printf, ADDR msg1fmt, ADDR msg2
    INVOKE scanf, ADDR in1fmt, ADDR n
    call power
    INVOKE printf, ADDR msg3fmt, ADDR msg3, ans
    ret
main     endp
```

```
power    proc
    push eax    ; save registers
    push ecx
    push edx
    mov ans,-1    ; default value for ans
    .if x<0 || n<0
    INVOKE printf, ADDR errfmt, ADDR errmsg1
    .else
    .if x==0 && n==0
    INVOKE printf, ADDR errfmt, ADDR errmsg2
    .else
    mov ecx,1    ; initialize ecx loop counter
    mov ans,1    ; initialize ans
    .while ecx <= n
    mov eax,ans    ; load eax with ans
    imul x        ; multiply eax by x
    mov ans,eax    ; store eax in ans
    inc ecx        ; increment eax loop countere
    .endw
    .endif
    .endif
    pop edx        ; restore registers
    pop ecx
    pop eax
    ret
power    endp
end
```

# Summary

- To invoke a procedure, use the CALL instruction followed by the name of the procedure.
- Always include a RET instruction in a procedure.
- Although more than one RET instruction can be included in a procedure, it is best to have only one and include it as the last instruction in a procedure.

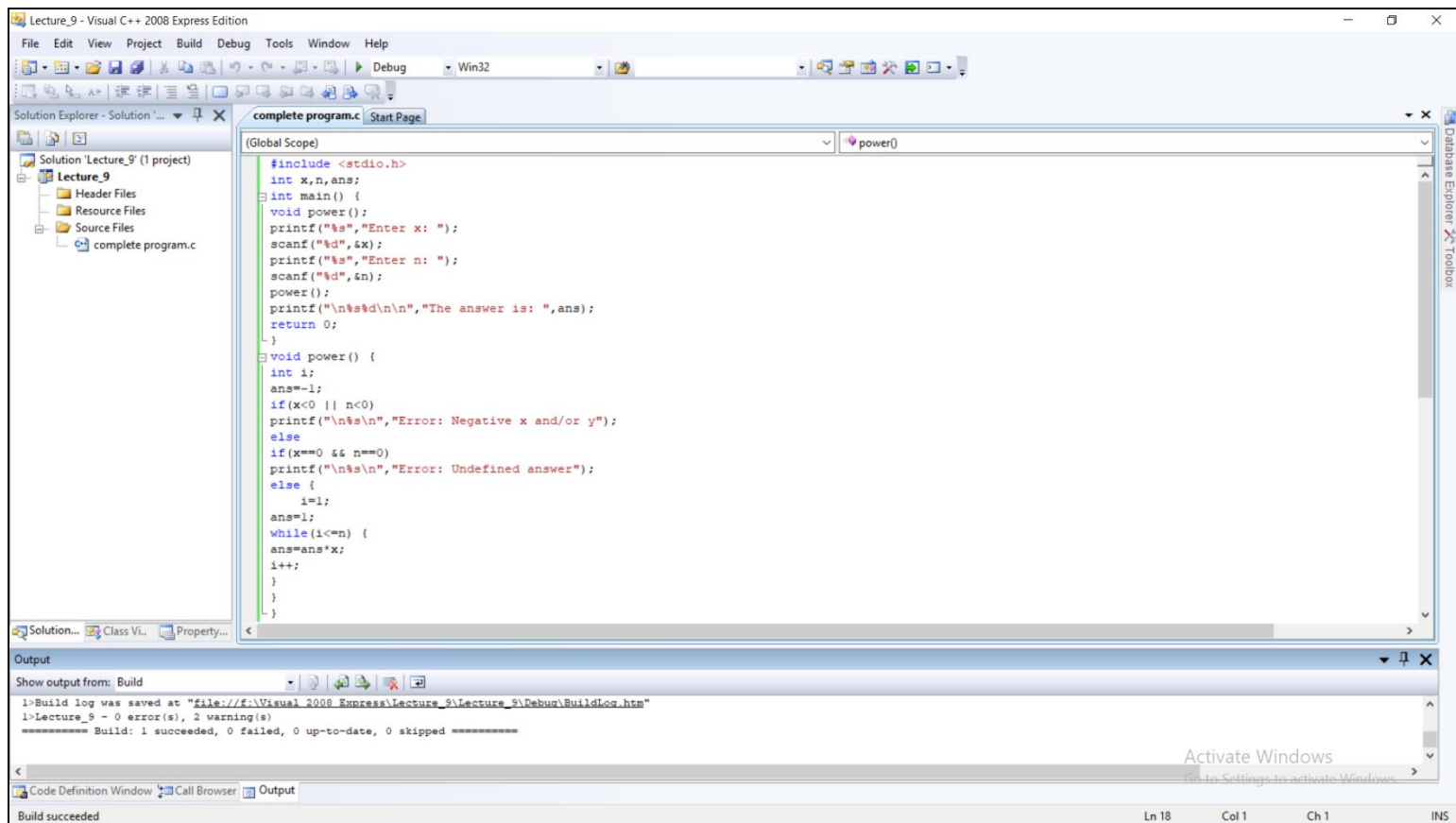
# **Microprocessor Programming**

## **Practical Works**

### **Implementing the Power Function in a Procedure**

# Implementing the Power Function in a Procedure

- The implementation of the given C program is described below:



```
#include <stdio.h>
int x,n,ans;
int main() {
void power();
printf("%s","Enter x: ");
scanf("%d",&x);
printf("%s","Enter n: ");
scanf("%d",&n);
power();
printf("\n%d\n","The answer is: ",ans);
return 0;
}
void power() {
int i;
ans=-1;
if(x<0 || n<0)
printf("\n\n","Error: Negative x and/or y");
else
if(x==0 && n==0)
printf("\n\n","Error: Undefined answer");
else {
i=1;
ans=1;
while(i<=n) {
ans=ans*x;
i++;
}
}
}
```

Output

Show output from: Build

```
1>Build log was saved at "file:///f:/Visual 2008 Express/Lecture_9/Lecture_9/Debug/BuildLog.htm"
1>Lecture_9 - 0 error(s), 2 warning(s)
***** Build: 1 succeeded, 0 failed, 0 up-to-date, 0 skipped *****
```

Build succeeded

# Implementing the Power Function in a Procedure

- The outputs of the given C program are described below:

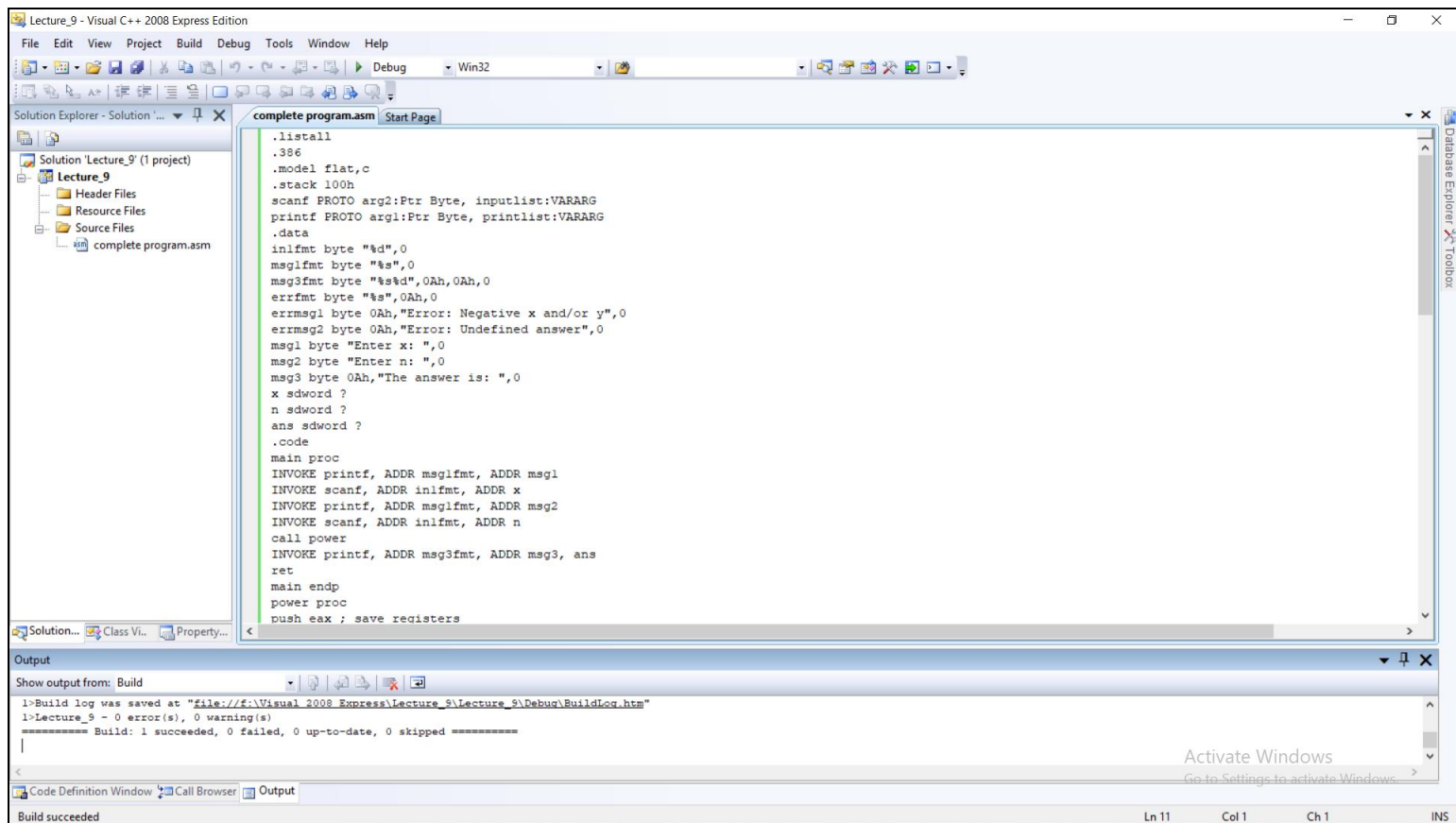
```
C:\WINDOWS\system32\cmd.exe
Enter x: 0
Enter n: 0
Error: Undefined answer
The answer is: -1
Press any key to continue .

C:\WINDOWS\system32\cmd.exe
Enter x: 8
Enter n: -12
Error: Negative x and/or y
The answer is: -1
Press any key to continue .

C:\WINDOWS\system32\cmd.exe
Enter x: 12
Enter n: 8
The answer is: 429981696
Press any key to continue . . . .
```

# Implementing the Power Function in a Procedure

- The implementation of the given MASM program is described below:



```
.listall
.386
.model flat,c
.stack 100h
scanf PROTO arg2:Ptr Byte, inputlist:VARARG
printf PROTO arg1:Ptr Byte, printlist:VARARG
.data
inlfmt byte "%d",0
msg1fmt byte "%s",0
msg3fmt byte "%s%d",0Ah,0Ah,0
errfmt byte "%s",0Ah,0
errmsg1 byte 0Ah,"Error: Negative x and/or y",0
errmsg2 byte 0Ah,"Error: Undefined answer",0
msg1 byte "Enter x: ",0
msg2 byte "Enter n: ",0
msg3 byte 0Ah,"The answer is: ",0
x sdword ?
n sdword ?
ans sdword ?
.code
main proc
INVOKE printf, ADDR msg1fmt, ADDR msg1
INVOKE scanf, ADDR inlfmt, ADDR x
INVOKE printf, ADDR msg1fmt, ADDR msg2
INVOKE scanf, ADDR inlfmt, ADDR n
call power
INVOKE printf, ADDR msg3fmt, ADDR msg3, ans
ret
main endp
power proc
push eax ; save registers
```

Output

```
Show output from: Build
1>Build log was saved at "file:///f:/Visual 2008 Express/Lecture_9/Lecture_9/Debug/BuildLog.htm"
1>Lecture_9 - 0 error(s), 0 warning(s)
***** Build: 1 succeeded, 0 failed, 0 up-to-date, 0 skipped *****
```

Build succeeded

# Implementing the Power Function in a Procedure

- The outputs of the given MASM program are described below:

The image shows three overlapping command prompt windows (cmd.exe) demonstrating the output of a MASM program. Each window has a title bar with the path 'C:\WINDOWS\system32\cmd.exe'.

- Top window:** Shows the program being executed with input `x: 0` and `n: 0`. The output is `Error: Undefined answer`, `The answer is: -1`, and `Press any key to continue .`
- Middle window:** Shows the program being executed with input `x: -8` and `n: 10`. The output is `Error: Negative x and/or y`, `The answer is: -1`, and `Press any key to continue .`
- Bottom window:** Shows the program being executed with input `x: 8` and `n: 10`. The output is `The answer is: 1073741824` and `Press any key to continue . . . .`

# **Microprocessor Programming**

## **Practical Assignments (Instructions)**

# Assignment 1

- Rewrite a complete assembly program for the given implementation of power function in a procedure without using high-level directives with only compare and jump instructions.

# **Microprocessor Programming**

## **Practical Assignments (Report)**

# Assignment 1

- A complete assembly program is described below:

```
.386
.model flat, c
.stack 100h

scanf PROTO arg2: Ptr Byte, inputlist: VARARG
printf PROTO arg1: Ptr Byte, printlist: VARARG

.data
in1fmt byte "%d", 0
msg1fmt byte "%s", 0
msg3fmt byte "%s%d", 0Ah, 0Ah, 0
errfmt byte "%s", 0Ah, 0
errmsg1 byte 0Ah, "Error: Negative x and/or y", 0
errmsg2 byte 0Ah, "Error: Undefined Answer", 0
msg1 byte "Enter x: ", 0
msg2 byte "Enter n: ", 0
msg3 byte 0Ah, "The answer is: ", 0
x sdword ?
n sdword ?
ans sdword ?

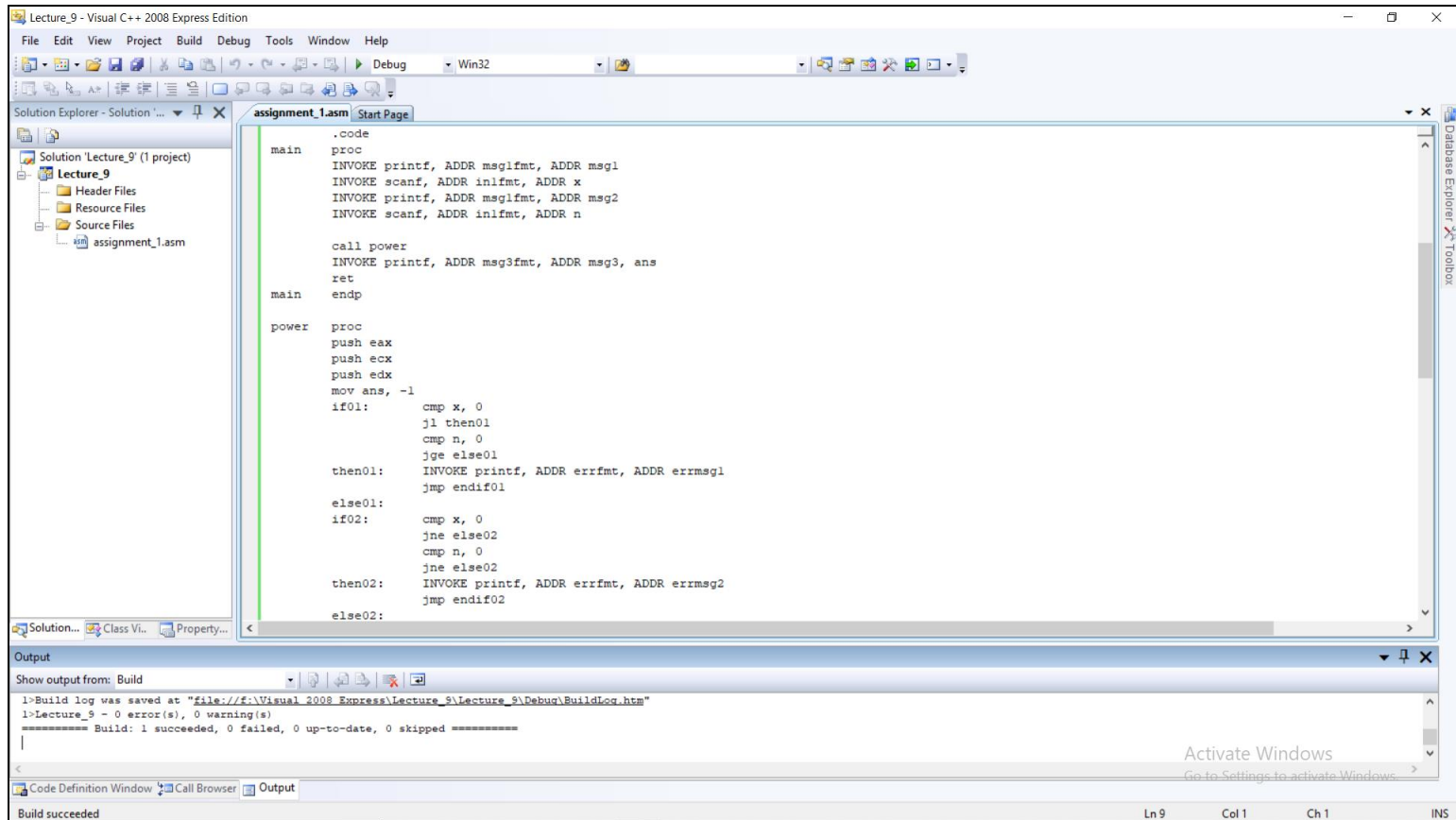
.code
main proc
    INVOKE printf, ADDR msg1fmt, ADDR msg1
    INVOKE scanf, ADDR in1fmt, ADDR x
    INVOKE printf, ADDR msg1fmt, ADDR msg2
    INVOKE scanf, ADDR in1fmt, ADDR n

    call power
    INVOKE printf, ADDR msg3fmt, ADDR msg3, ans
    ret
main endp
```

```
power proc
    push eax
    push ecx
    push edx
    mov ans, -1
if01:    cmp x, 0
        jl then01
        cmp n, 0
        jge else01
then01:  INVOKE printf, ADDR errfmt, ADDR errmsg1
        jmp endif01
else01:
if02:    cmp x, 0
        jne else02
        cmp n, 0
        jne else02
then02:  INVOKE printf, ADDR errfmt, ADDR errmsg2
        jmp endif02
else02:
        mov ecx, 1
        mov ans, 1
while02: cmp ecx, n
        jg endw02
        mov eax, ans
        imul x
        mov ans, eax
        inc ecx
        jmp while02
endw02:  nop
endif02: nop
endif01: nop
    pop edx
    pop ecx
    pop eax
    ret
power endp
end
```

# Assignment 1

- A complete assembly program is implemented as follow:



```
.code
main
proc
    INVOKE printf, ADDR msg1fmt, ADDR msg1
    INVOKE scanf, ADDR in1fmt, ADDR x
    INVOKE printf, ADDR msg1fmt, ADDR msg2
    INVOKE scanf, ADDR in1fmt, ADDR n

    call power
    INVOKE printf, ADDR msg3fmt, ADDR msg3, ans
    ret
main
endp

power
proc
    push eax
    push ecx
    push edx
    mov ans, -1
    if01:    cmp x, 0
            j1 then01
            cmp n, 0
            jge else01
    then01: INVOKE printf, ADDR errfmt, ADDR errmsg1
            jmp endif01
    else01:
    if02:    cmp x, 0
            jne else02
            cmp n, 0
            jne else02
    then02: INVOKE printf, ADDR errfmt, ADDR errmsg2
            jmp endif02
    else02:
```

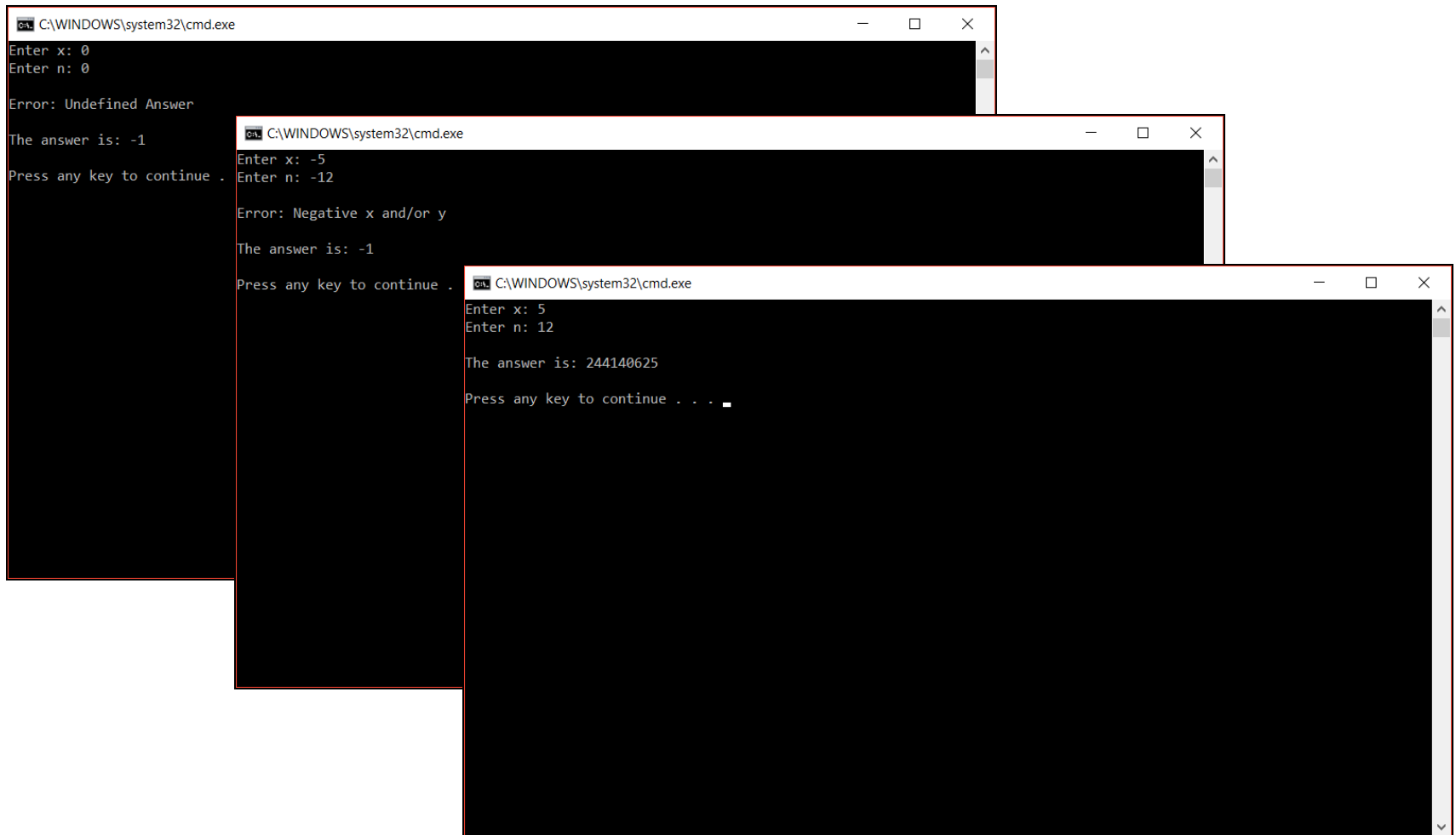
Output

```
Show output from: Build
1>Build log was saved at "file:///f:/Visual 2008 Express/Lecture_9/Lecture_9/Debug/BuildLog.htm"
1>Lecture_9 - 0 error(s), 0 warning(s)
***** Build: 1 succeeded, 0 failed, 0 up-to-date, 0 skipped *****
```

Build succeeded

# Assignment 1

- The corresponding outputs are as follow:



```
C:\WINDOWS\system32\cmd.exe
Enter x: 0
Enter n: 0

Error: Undefined Answer

The answer is: -1
Press any key to continue .

C:\WINDOWS\system32\cmd.exe
Enter x: -5
Enter n: -12

Error: Negative x and/or y

The answer is: -1
Press any key to continue .

C:\WINDOWS\system32\cmd.exe
Enter x: 5
Enter n: 12

The answer is: 244140625
Press any key to continue . . . .
```

# Next Lecture

- Macros
- Conditional Assembly

**Thank You**